MENOUFIA UNIVERSITY
FACULTY OF ENGINEERING
SHEBIN ELKOM
First SEMESTER EXAMINATION ACADEMIC YEAR:- 2017/2018


DEPARTMENT:PROD.ENG.\&MECH.DESIGN POST GRADUATE MASTER LEVEL 600 SUBJECT/CODE:MECHANISMS/ PRE615 TIME ALLOWED: 3 HOURS
DATE:- 26/5/2018

This exam measures the following iLOs $\left(a_{4}, a_{13}, a_{19}, b_{2}, b_{17}, c_{7}\right)$

## ANSWER THE FOLLOWING QUESTIONS :- ( 100 MARKS )

## Question No. 1:-

In the mechanism shown in Fig. 1, using the position analysis of loop closure equations to drive the following as fuctions of $\theta_{2}$ :-
1 -The position angles of link $3, \theta_{3}=f\left(\theta_{2}\right)$, and link $4, \theta_{4}=f\left(\theta_{2}\right)$,
2 -The position angle of link $5, \theta_{5}=f\left(\theta_{2}\right)$ and also, the vertical position of slider $C, Y_{c}=f\left(\theta_{2}\right)$.
2 -The angular velorities of link $3, \omega_{3}=f\left(\theta_{2}\right)$ and link $4, \omega_{4}=f\left(\theta_{2}\right)$.
3 -The angular acceleration of link $4, \alpha_{4}=f\left(\theta_{2}\right)$.

## Question No. 2 :-

Consider the mechanism shown in Fig. 2, crank $2\left(\mathrm{O}_{2} \mathrm{~A}\right)$ rotates at a constant agular velocity $\omega_{2}=18 \mathrm{rad} / \mathrm{s}$, in clockwise direction. Determine the velocity and acceleration of point B by using method of vector mathematics analysis. Also, find the accelerations of points of mass center for link 3 ( the point $\mathrm{g}_{3}$ ) and link 4 ( the point $\mathrm{g}_{4}$ ). Select coordinate axes as shown with point $\left(\mathrm{O}_{2}\right)$ as the origin of the fixed axis $X Y$-system and the point $A$ as the origin of the moving axis xy-system .
Given:- $\mathrm{O}_{2} \mathrm{~A}=6 \mathrm{~cm}, \mathrm{AB}=13 \mathrm{~cm}, \mathrm{O}_{4} \mathrm{~B}=4 \mathrm{~cm}, \mathrm{O}_{2} \mathrm{O}_{4}=16 \mathrm{~cm}, \mathrm{Ag}_{3}=\mathrm{B} \mathrm{g}_{3}=7 \mathrm{~cm}, \mathrm{O}_{4} \mathrm{~g}_{4}=\mathrm{B} \mathrm{g} \mathrm{g}_{4}=2.5 \mathrm{~cm}$.


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Fig. 2 is shown the mechanism of problem 2, for which the velocity and acceleration analysis has been made. The masses of links $m_{2}=2 \mathrm{~kg}, m_{3}=10 \mathrm{~kg}, m_{4}=8 \mathrm{~kg}$, and mass moment of inertia for the links $\mathrm{I}_{\mathrm{g} 3}=0.012 \mathrm{~kg} \cdot \mathrm{~m}^{2}, \mathrm{I}_{\mathrm{g} 4}=0.008 \mathrm{~kg} \cdot \mathrm{~m}^{2}$, where $\mathrm{g}_{3}$ and $\mathrm{g}_{4}$ are centers of gravity of the links 3 and 4 respectively. Assume the inertia caused by link $2\left(\mathrm{O}_{2} \mathrm{~A}\right)$ is very small and can be neglected. Considering the effect of the inertia forces only, determine the bearing forces on points $\mathrm{O}_{2}, \mathrm{O}_{4}$ and the torque T at point $\mathrm{O}_{2}$ by superposition method using unit vectors to maintain the mechanism in equilibrium .

Question No. 4 :-
A spring -loaded governor, Fig.3, has the balls attached to the vertical arms of bell-crank levers. The horizontal arms of which lift the sleeve $S$ against the force exerted by a spring. The mass of each ball is 2 kg , the lengths of the vertical and horizontal arms of the bell-crank levers are $a=16 \mathrm{~cm}$ and $b=12 \mathrm{~cm}$ respectively. The extreme radii of rotation of the balls are 10 cm and 14 cm . The governor sleeve begins to lift at speed to 250 rpm and reaches its highest position with increase of speed to 270 rpm. Determine the required stiffness of the spring and the average force exerted at the sleeve for an increase of the speed $2 \%$ above that corresponding to a radius of rotation of 12 cm .


Fig. 2


GOOD LUCK
Dr.R. Aouelnasr
With our best wishes.


